

Micro from macro

(and applications in event generators)

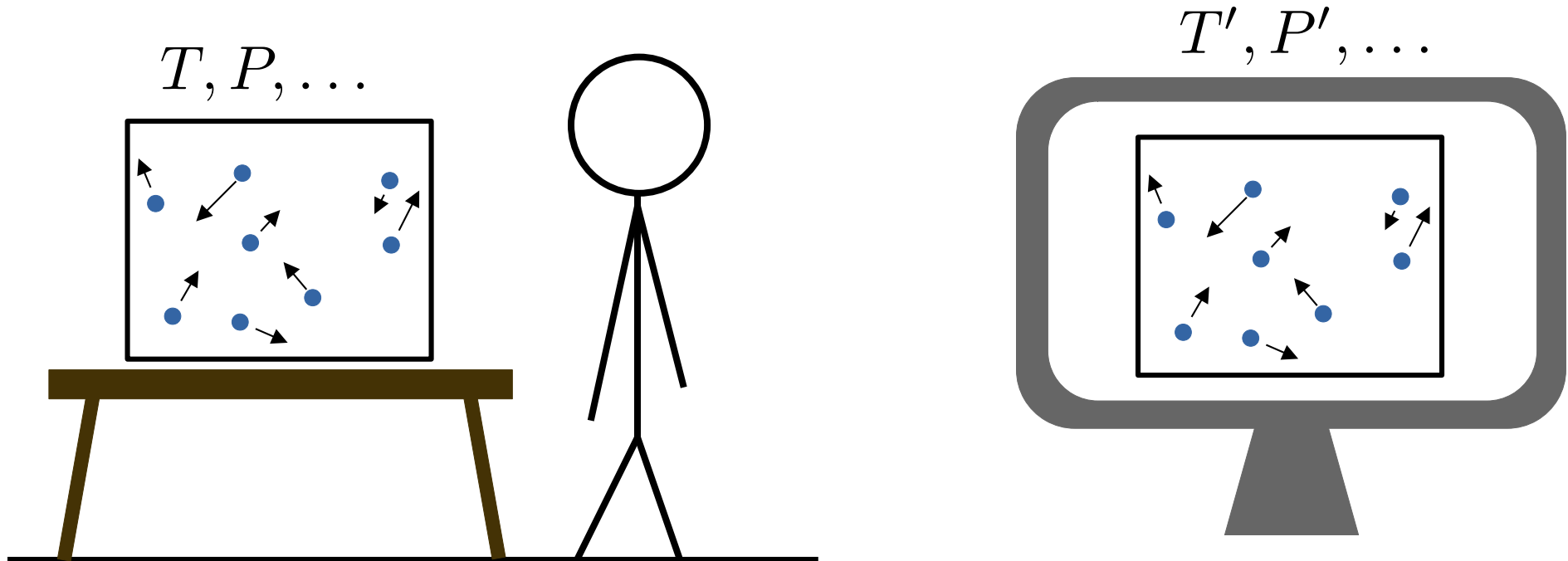
ATLAS Lunch

Tony Menzo

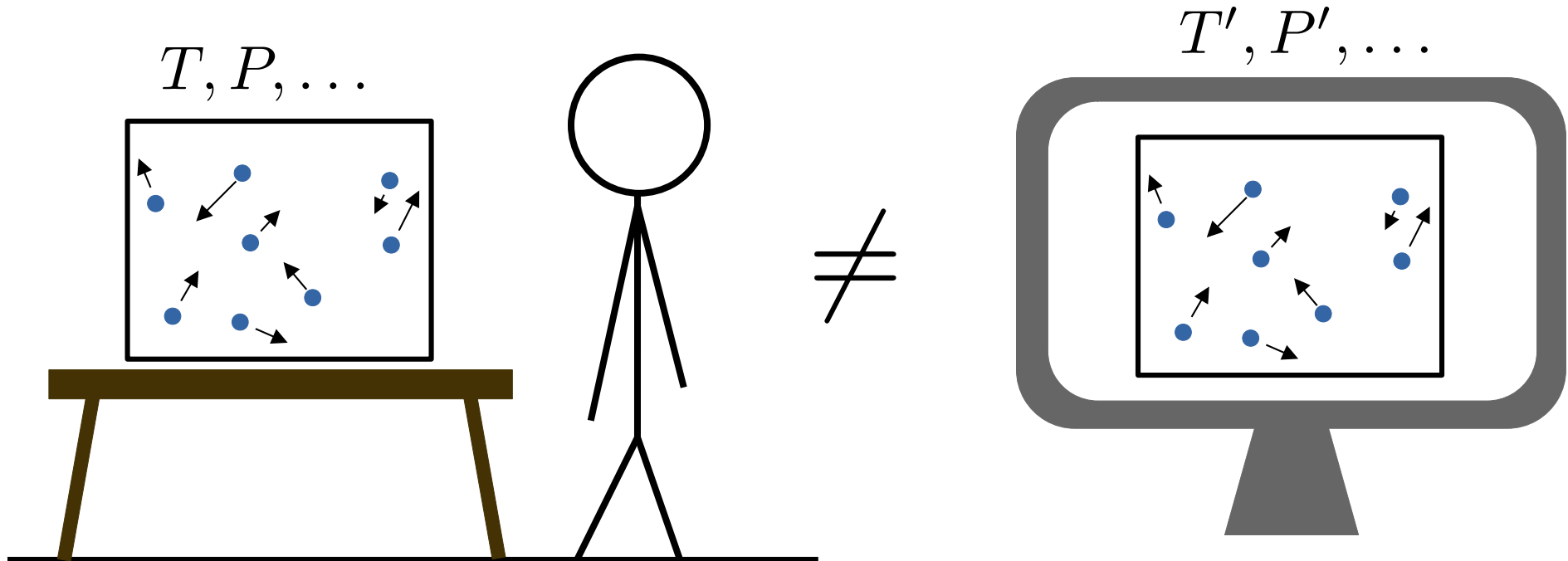
PhD candidate, University of Cincinnati

MLHAD The text 'MLHAD' is rendered in a large, black, serif font. To the right of the letters 'H' and 'A', there is a decorative graphic in green. It consists of several horizontal lines with small circles at their ends, resembling particle tracks. Some of these lines are connected by vertical lines, forming a network of paths that extend to the right of the text.

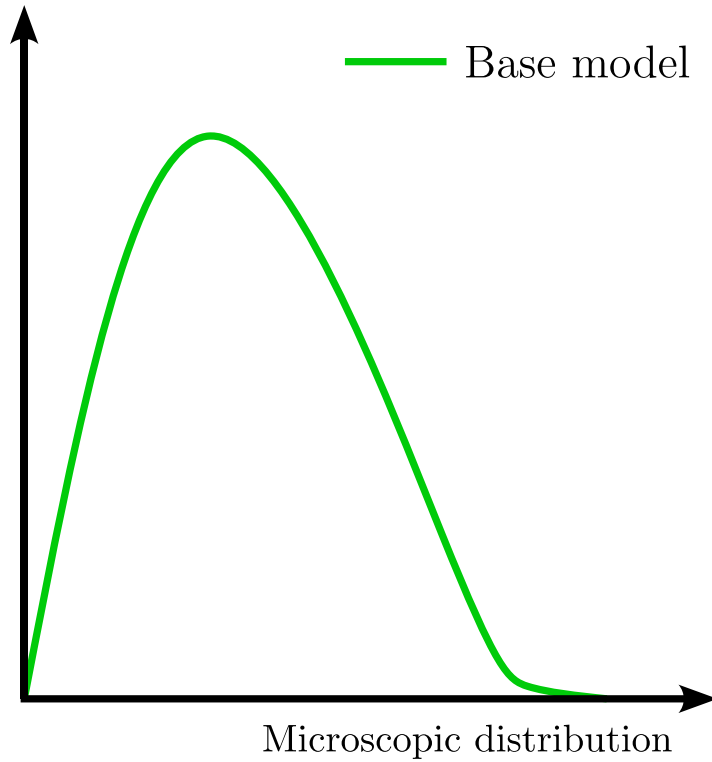
The problem.



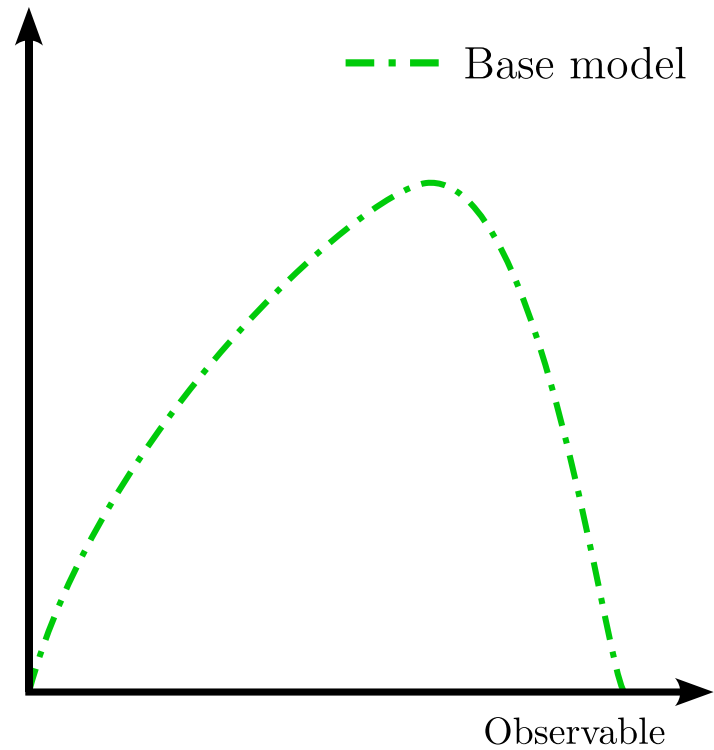
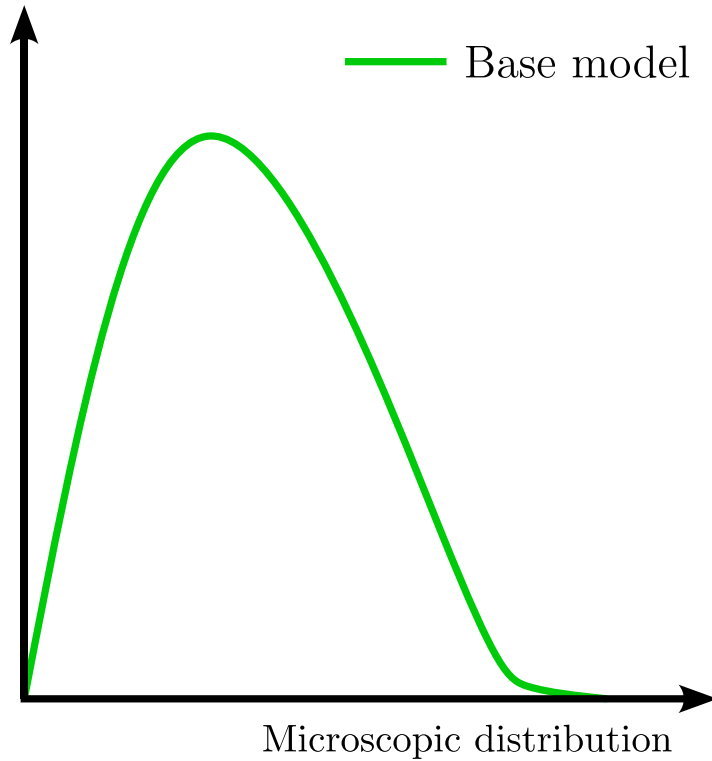
The problem.



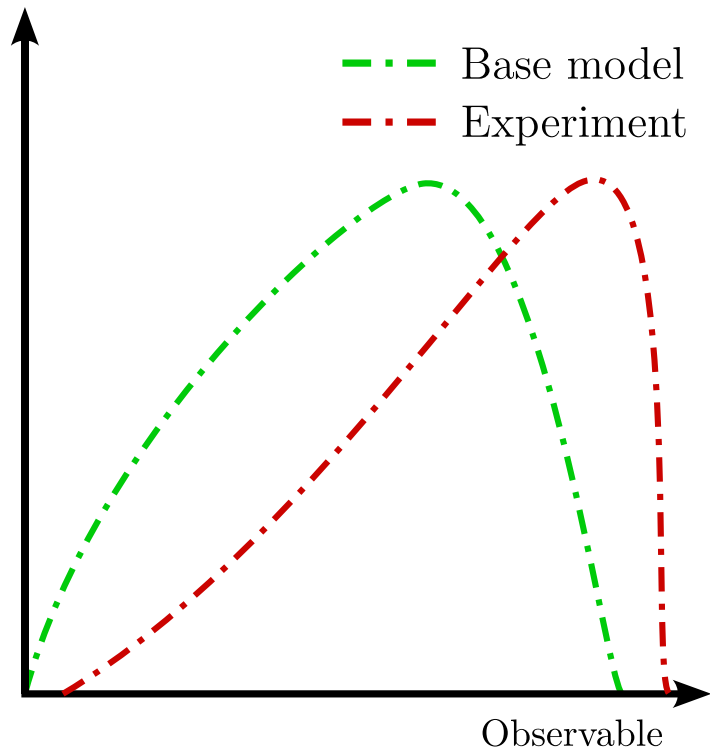
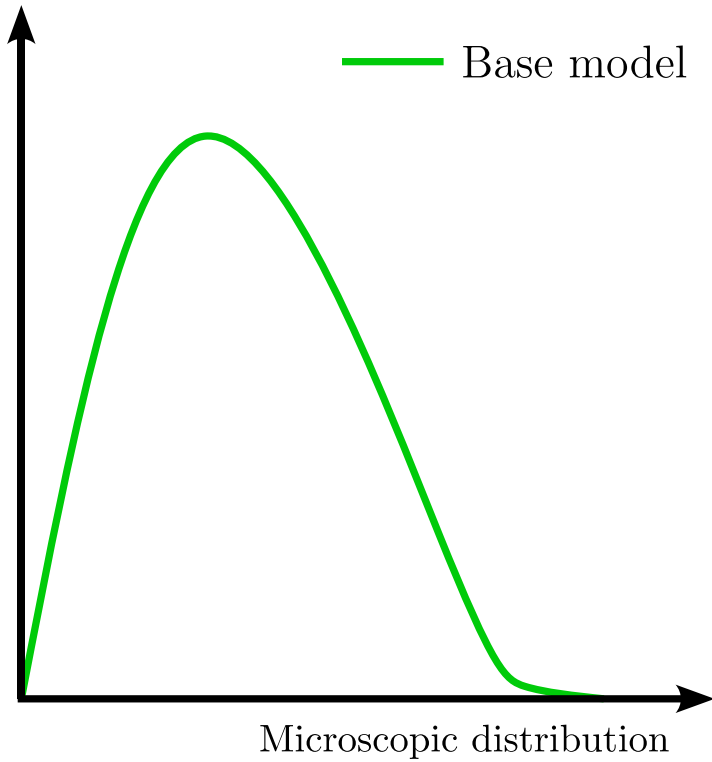
A potential solution



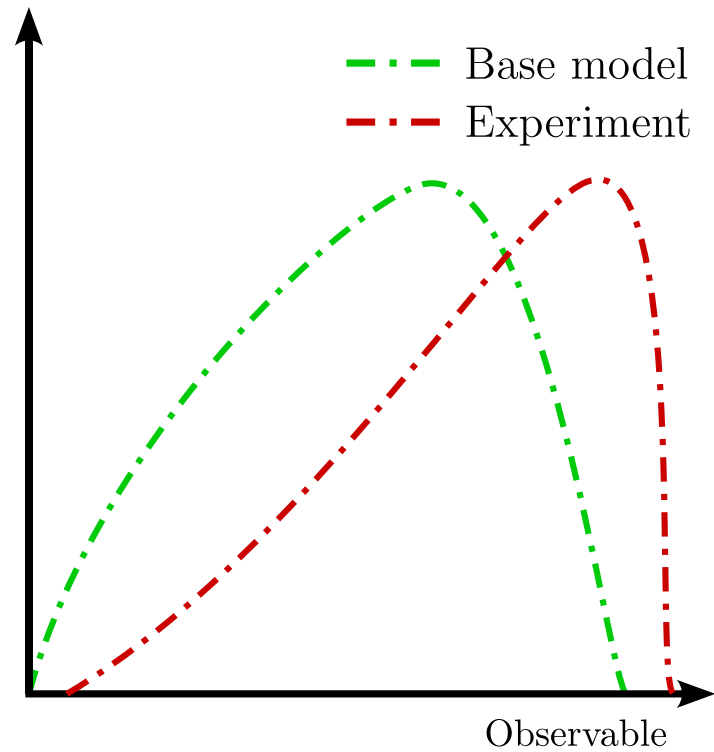
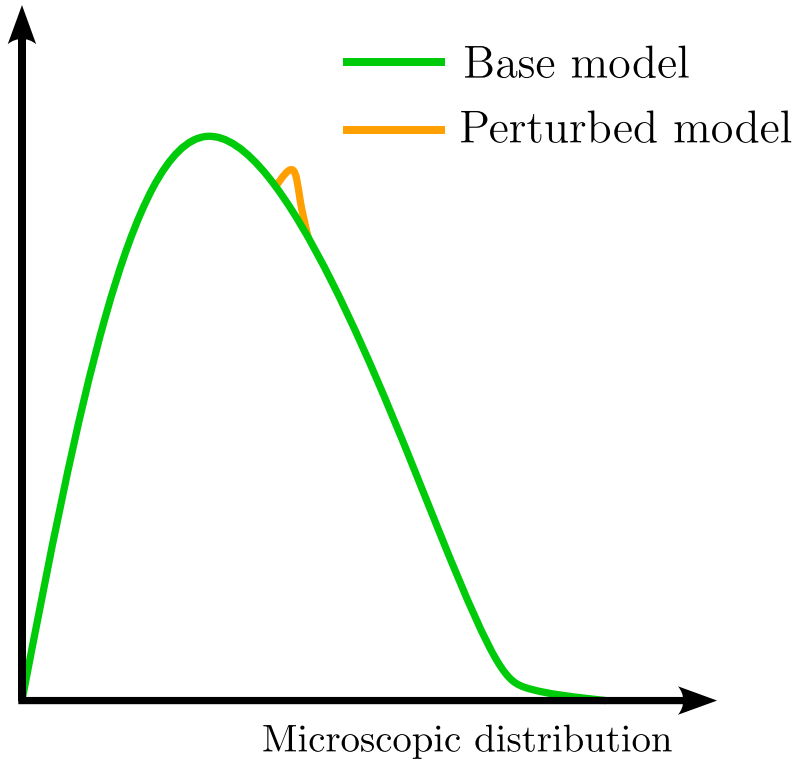
A potential solution



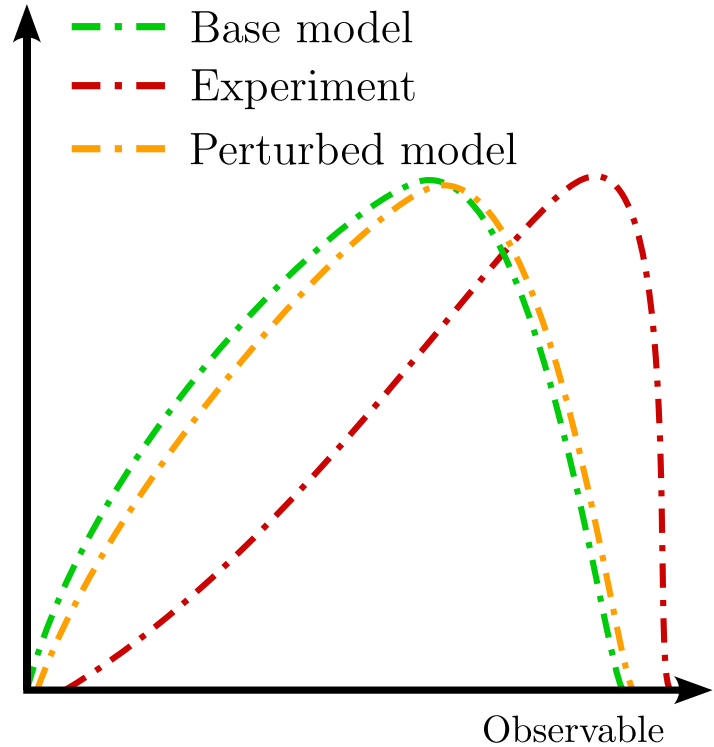
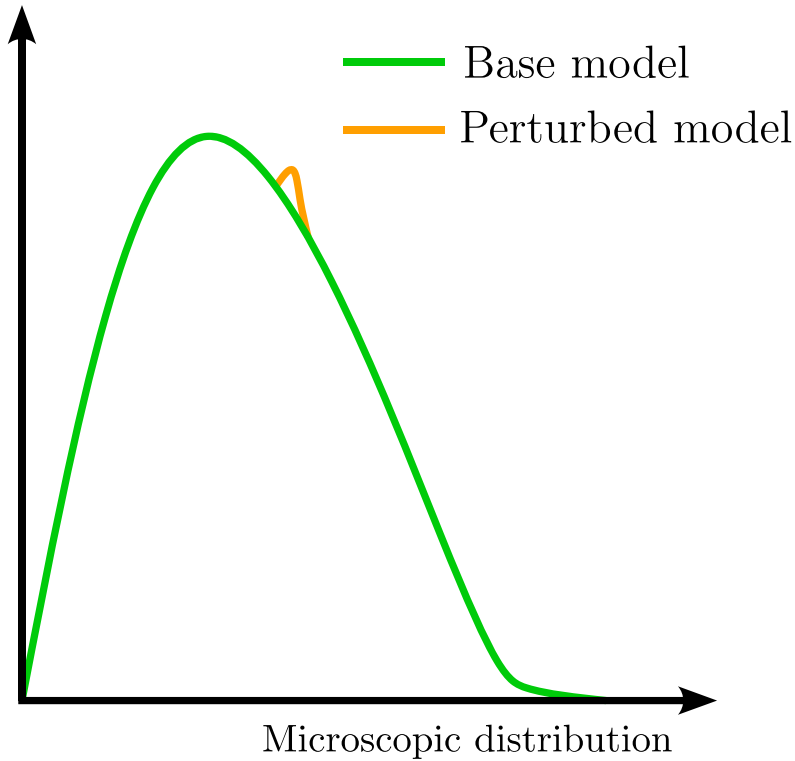
A potential solution



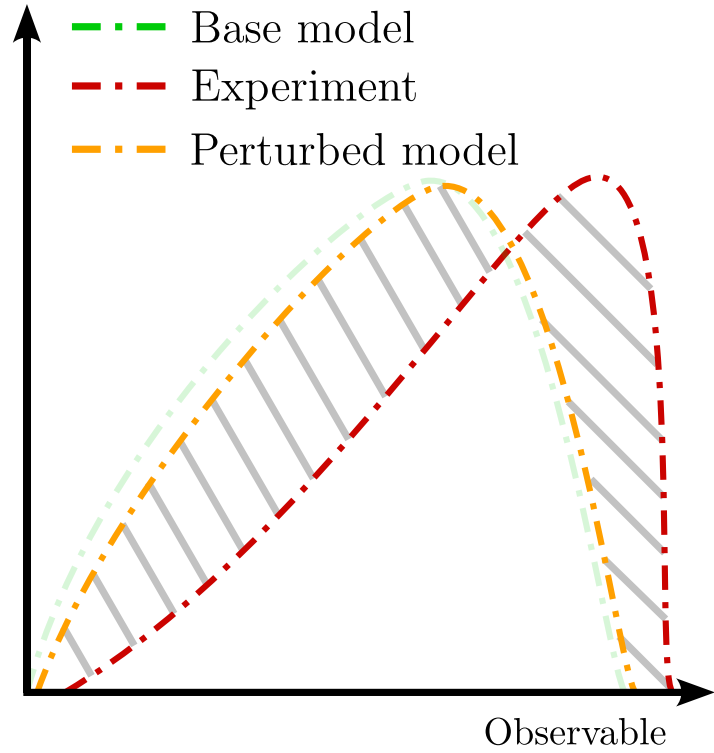
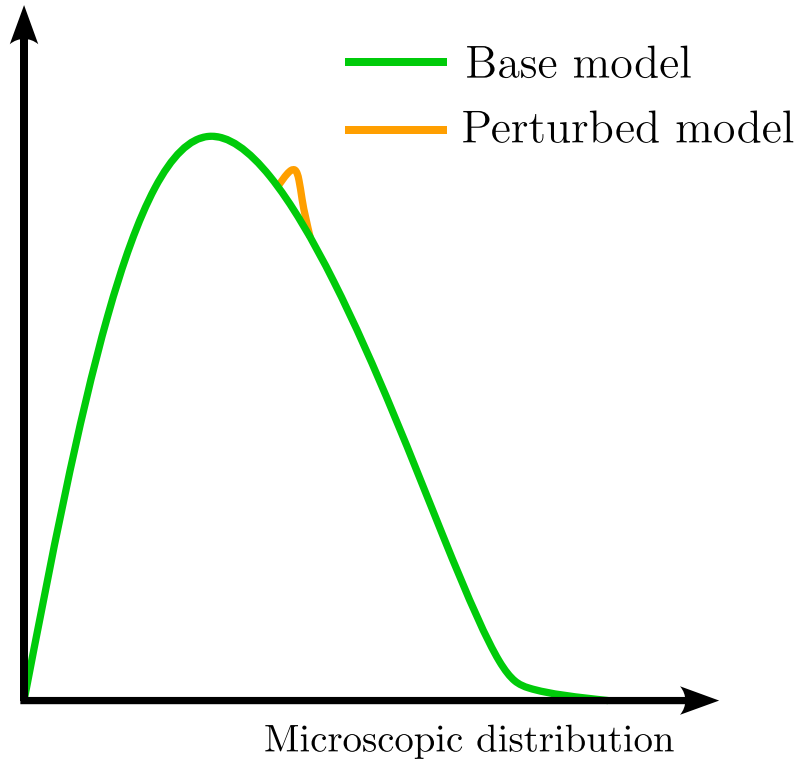
A potential solution



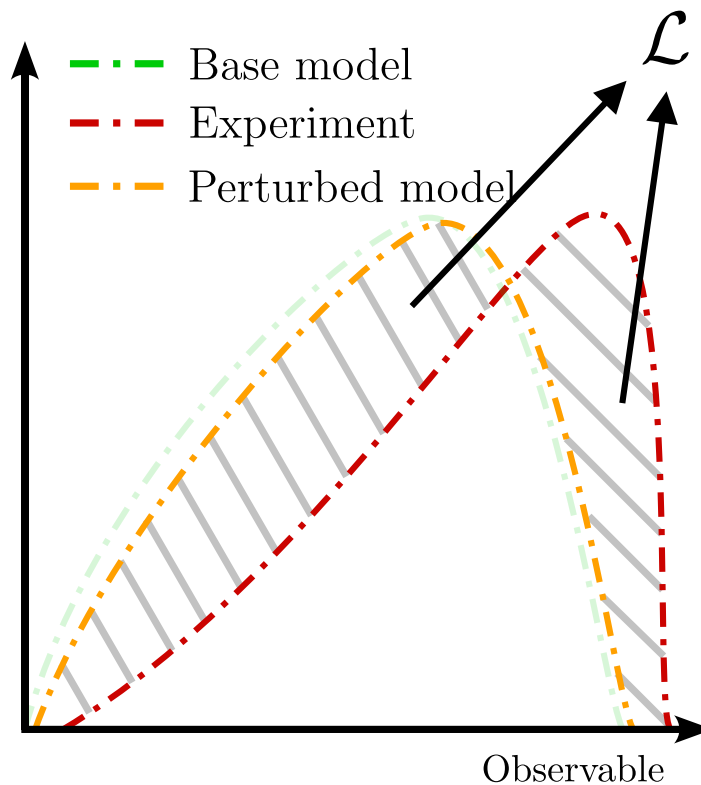
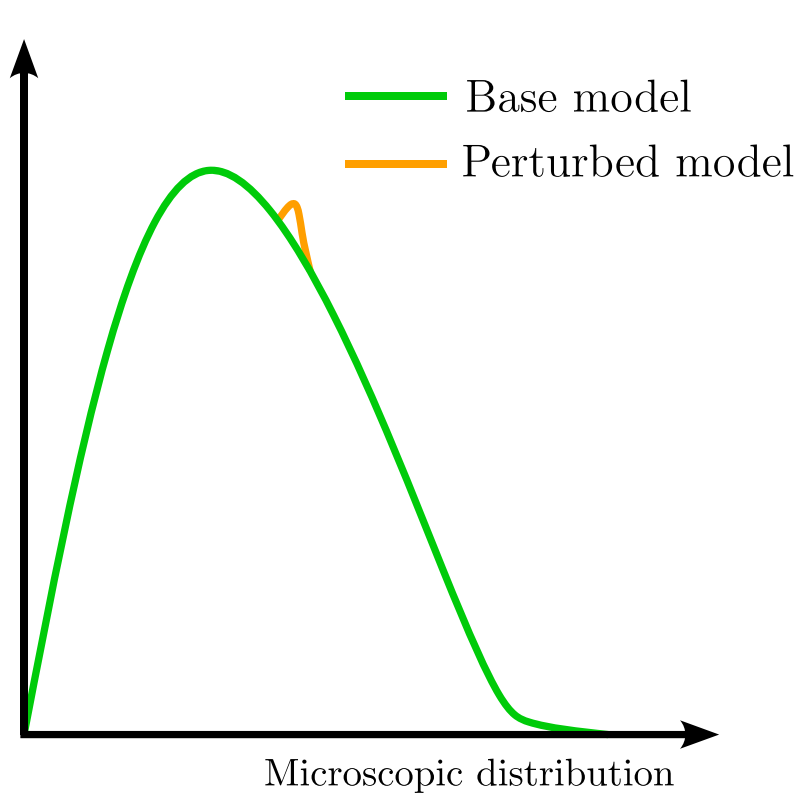
A potential solution



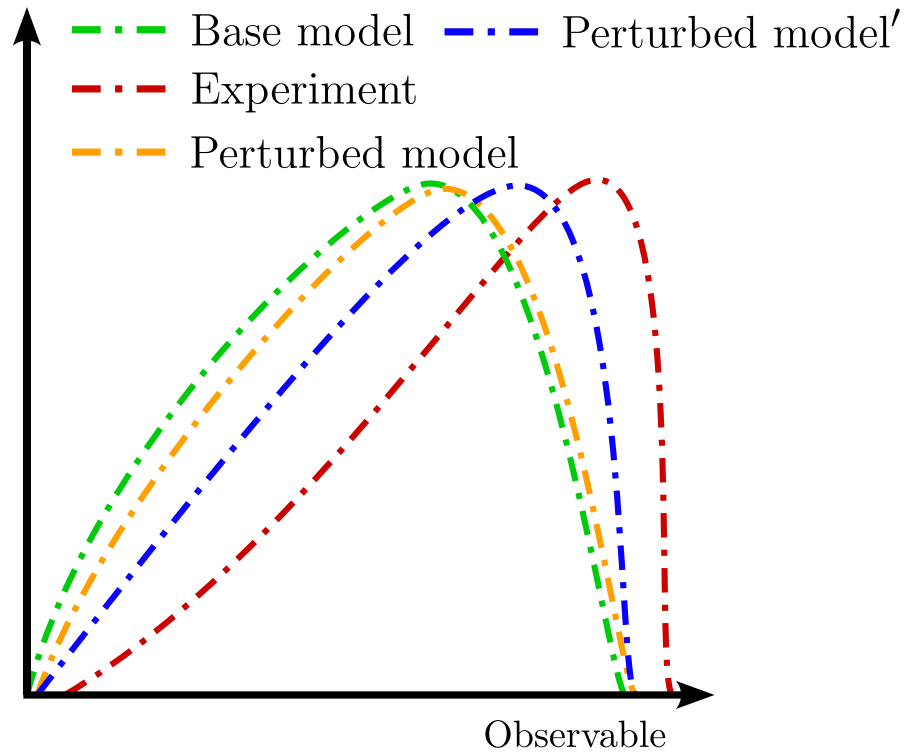
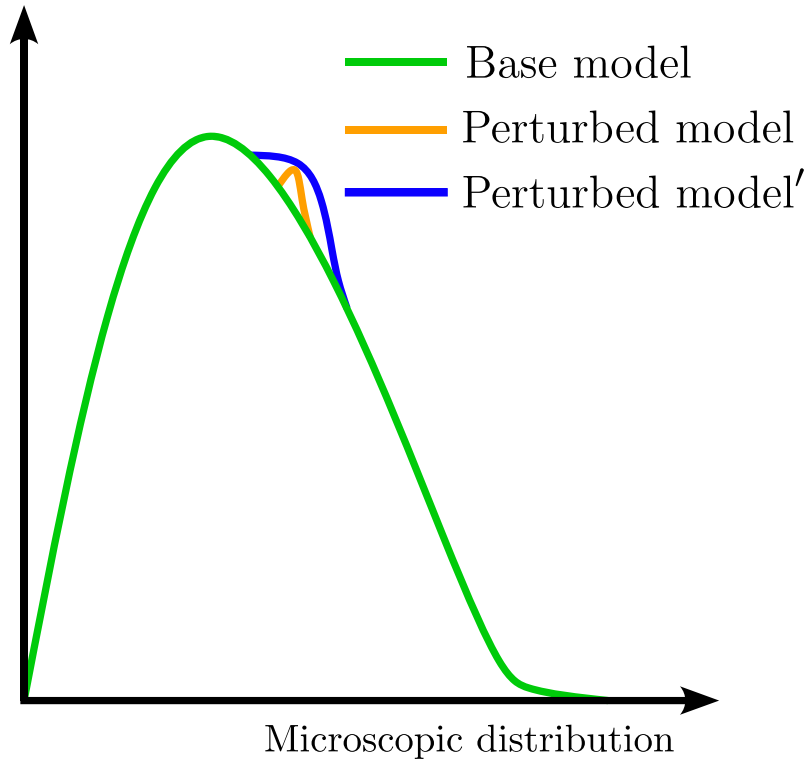
A potential solution



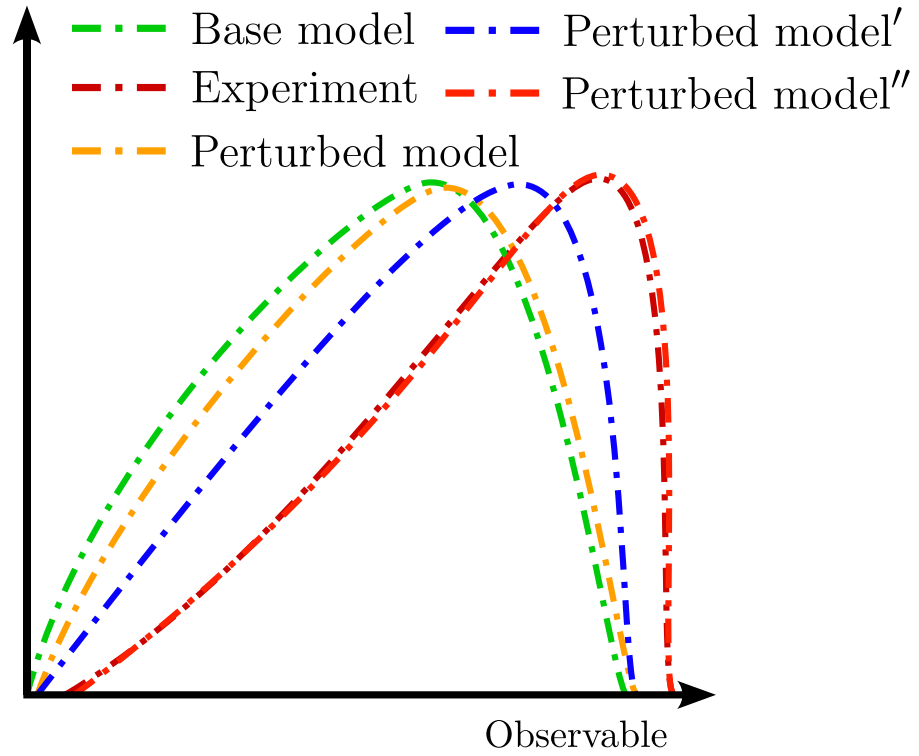
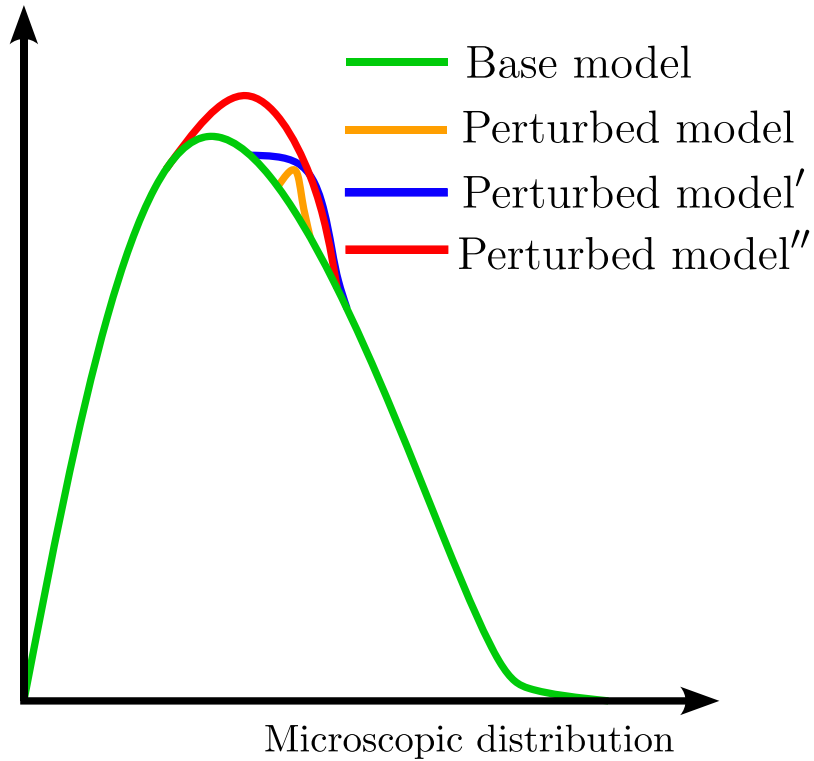
A potential solution



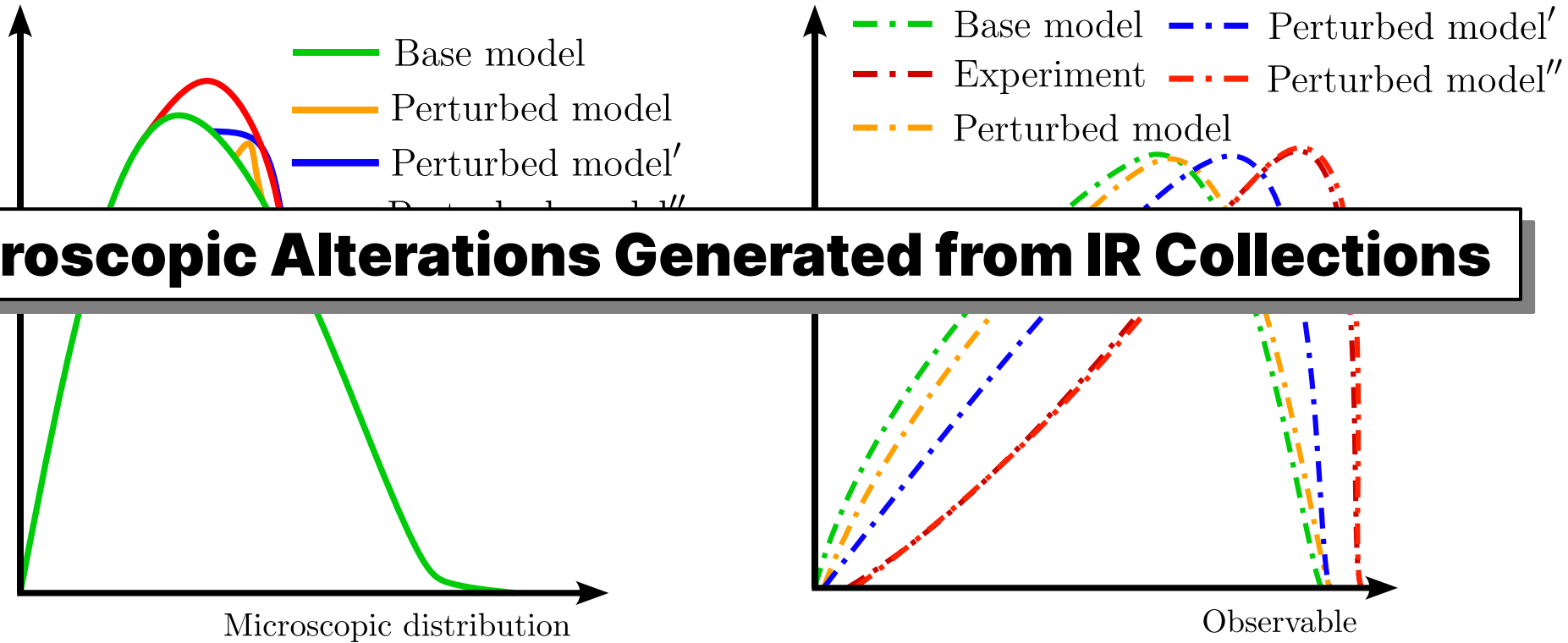
A potential solution



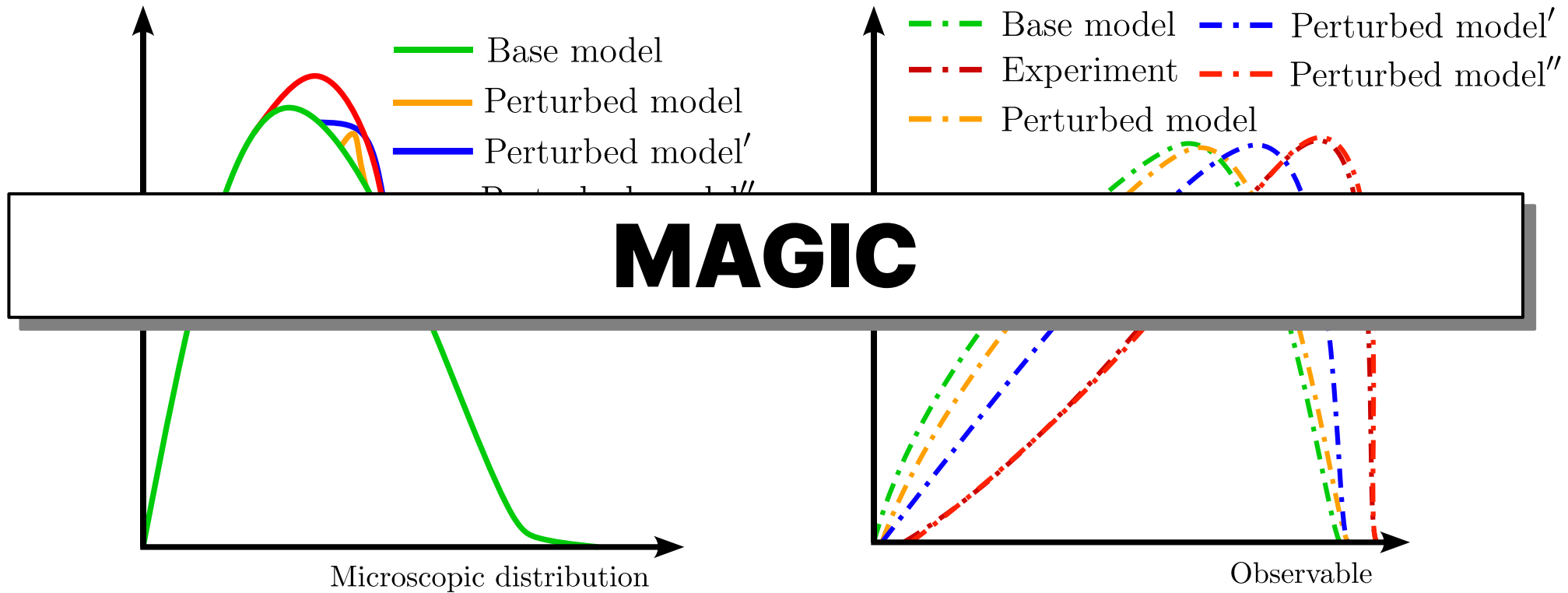
A potential solution



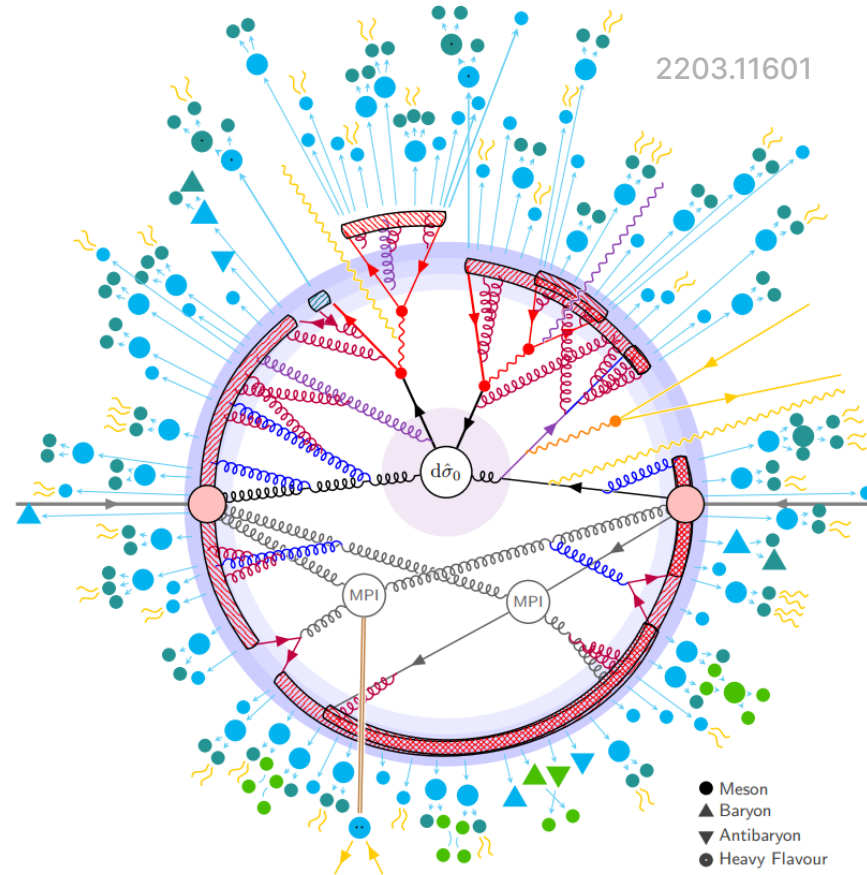
A potential solution



A potential solution



Hadronization



Considerations

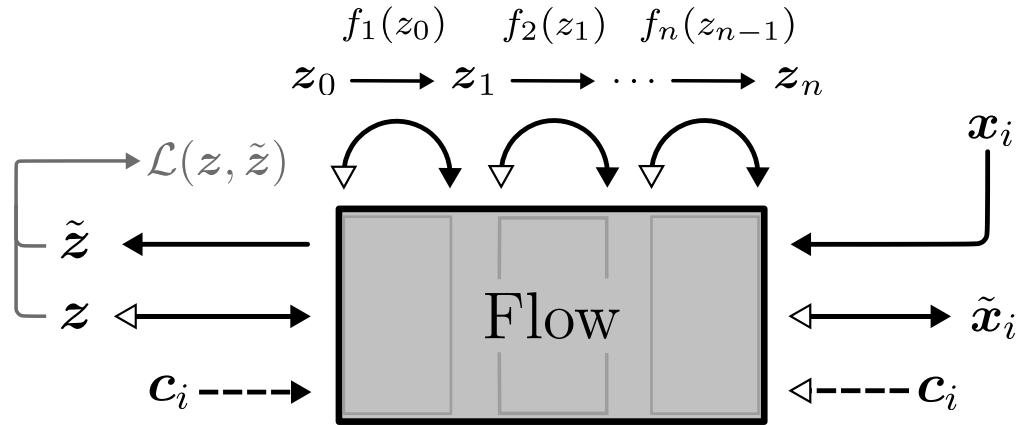
1. Error analysis
2. Incorporation into event generation
3. How to check that we're not masking other issues (e.g. parton shower effects)
4. How should the new solution be interpreted
5. Other applications

BACK-UP

Invertible neural networks (INN)

a.k.a normalizing flow

Learn a composition of n independent bijective transformations that relate a probability distribution $p_Z(z)$ on latent space Z to the target distribution $p_X(x)$ on target space X .



The probability distribution for the random variable $x = f(z)$ is given by

$$p_X^f(x) = p_Z(z) |\det J_f(z)|^{-1}$$

$$J_f = \partial f / \partial x$$

For n iterative transformations:

$$p_X^F(x) = p_Z(z_0) \prod_{i=1}^n |\det J_{f_i}(z_{i-1})|^{-1}$$

Invertible neural networks (INN)

a.k.a normalizing flow

Invertible Real NVP transformations:

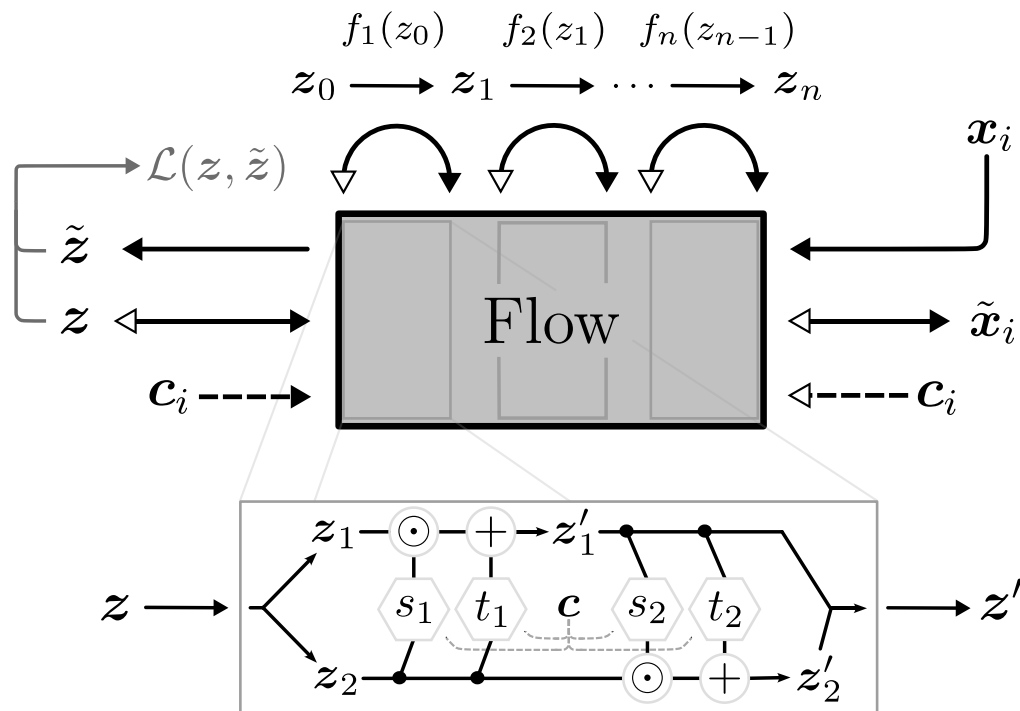
$$z'_1 = z_1 \odot \exp(s_1(z_2)) + t_1(z_2),$$

$$z'_2 = z_2 \odot \exp(s_2(z'_1)) + t_2(z'_1),$$

Inverse:

$$z_2 = (z'_2 - t(z'_1)) \odot \exp(-s(z'_1)),$$

$$z_1 = (z'_1 - t(z_2)) \odot \exp(-s(z_2)),$$



Invertible neural networks (INN)

a.k.a normalizing flow

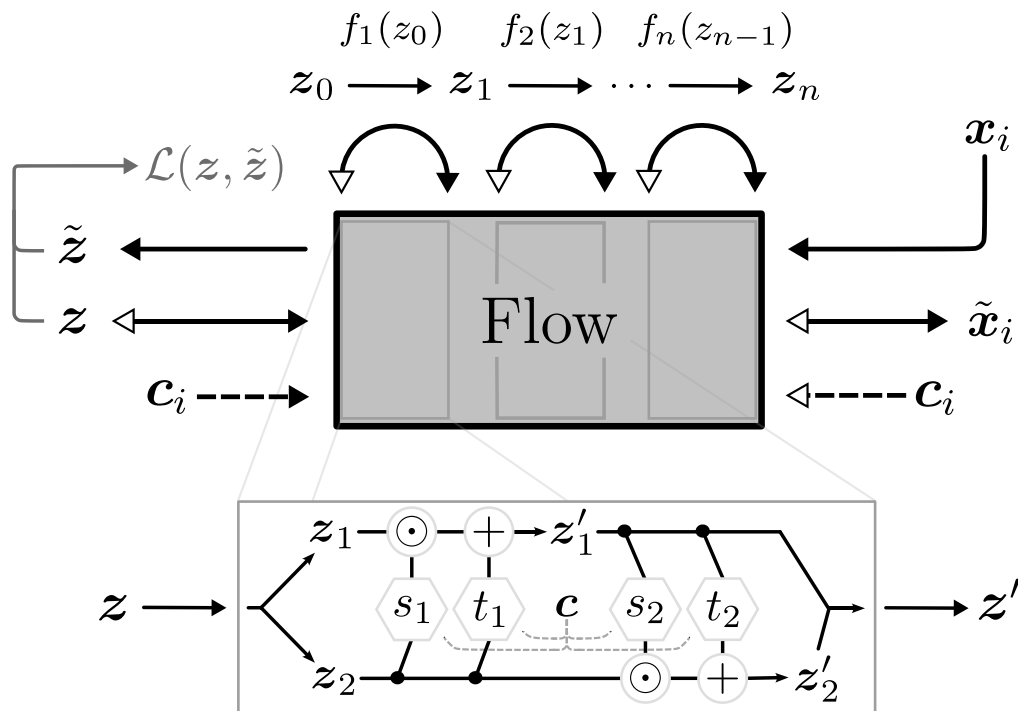
Invertible Real NVP transformations:

$$z'_1 = z_1 \odot \exp(s_1(z_2)) + t_1(z_2),$$

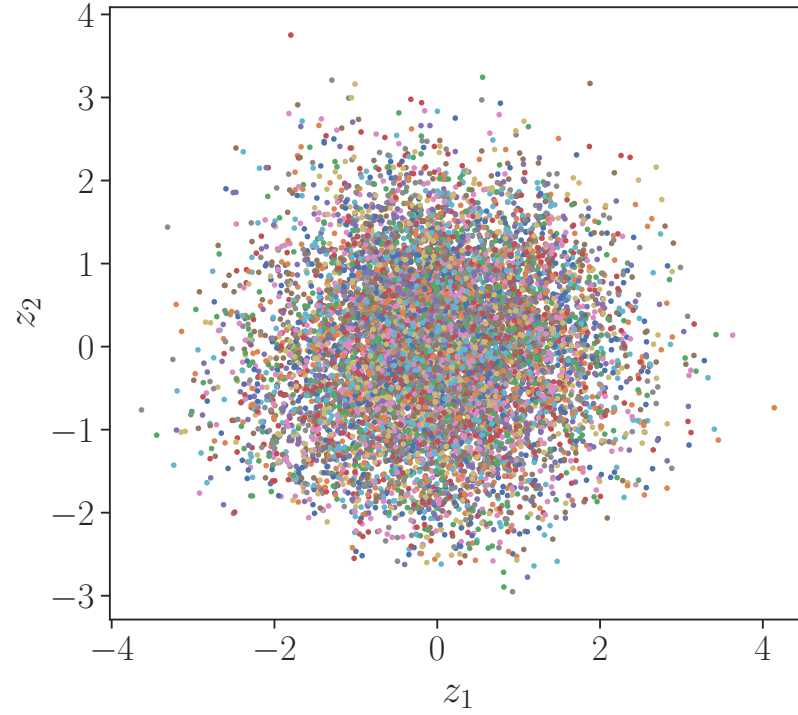
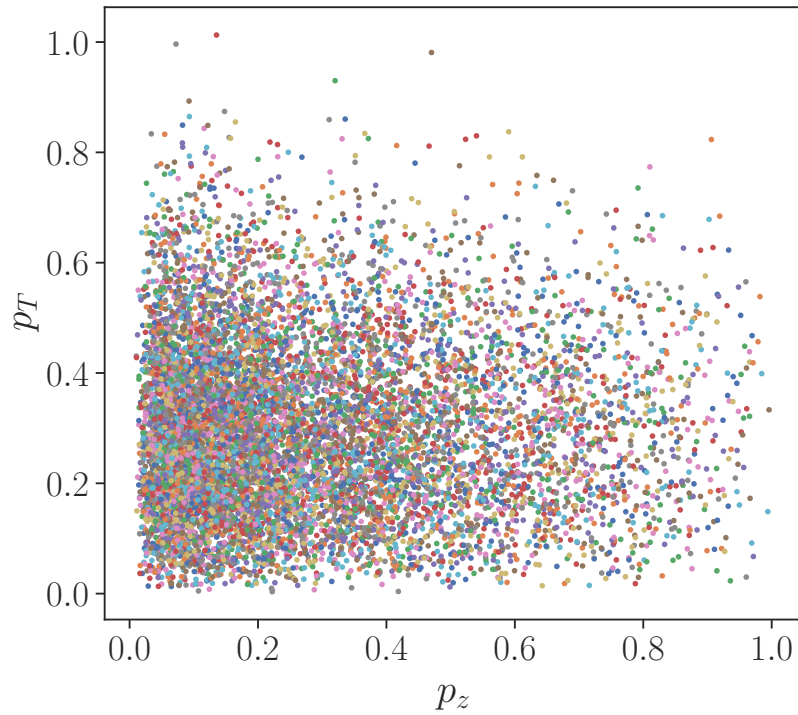
$$z'_2 = z_2 \odot \exp(s_2(z'_1)) + t_2(z'_1),$$

Scale transform

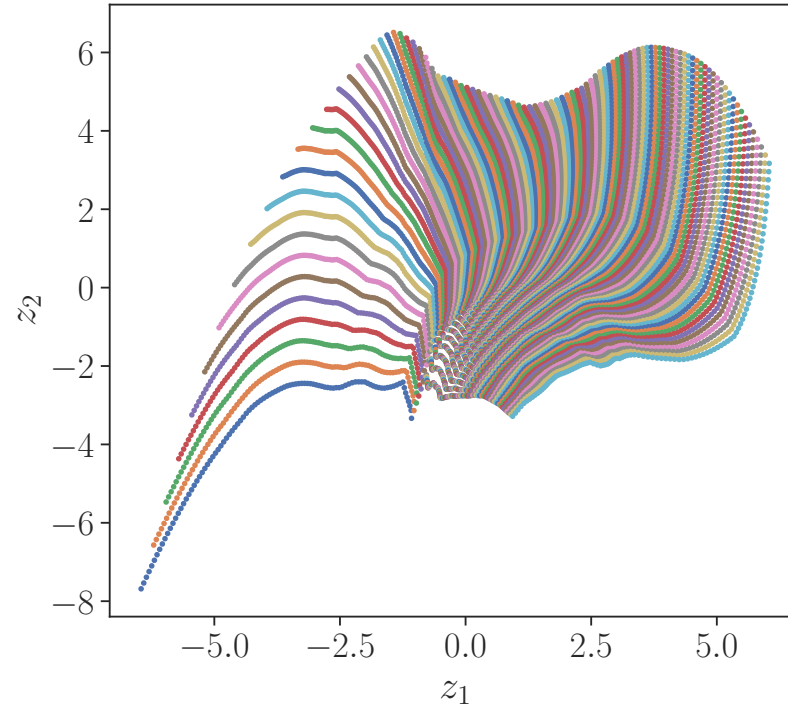
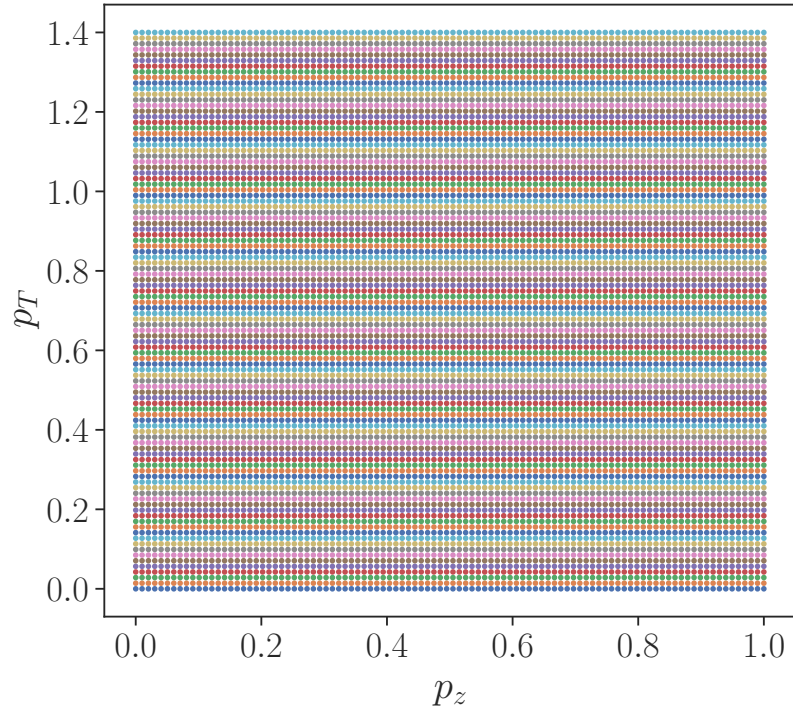
Translation transform



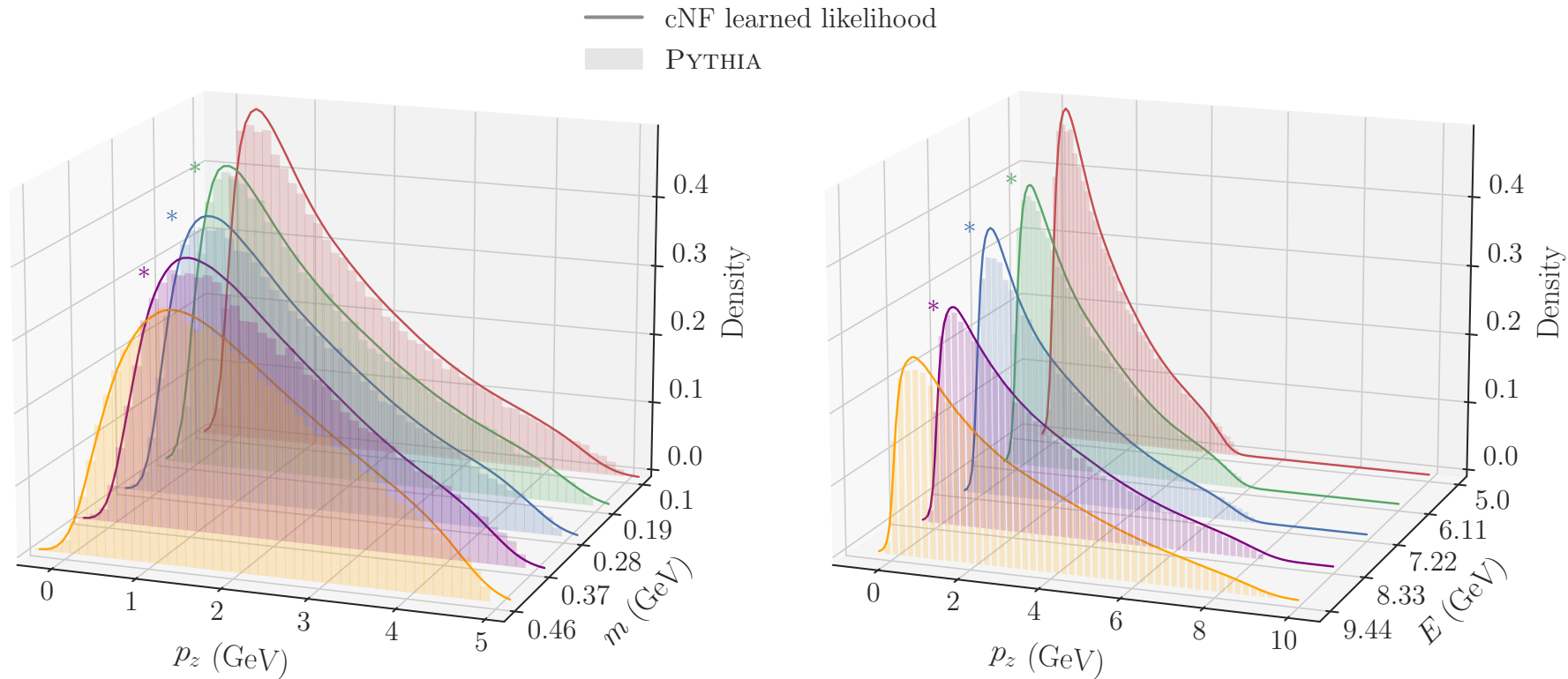
INN learned mapping



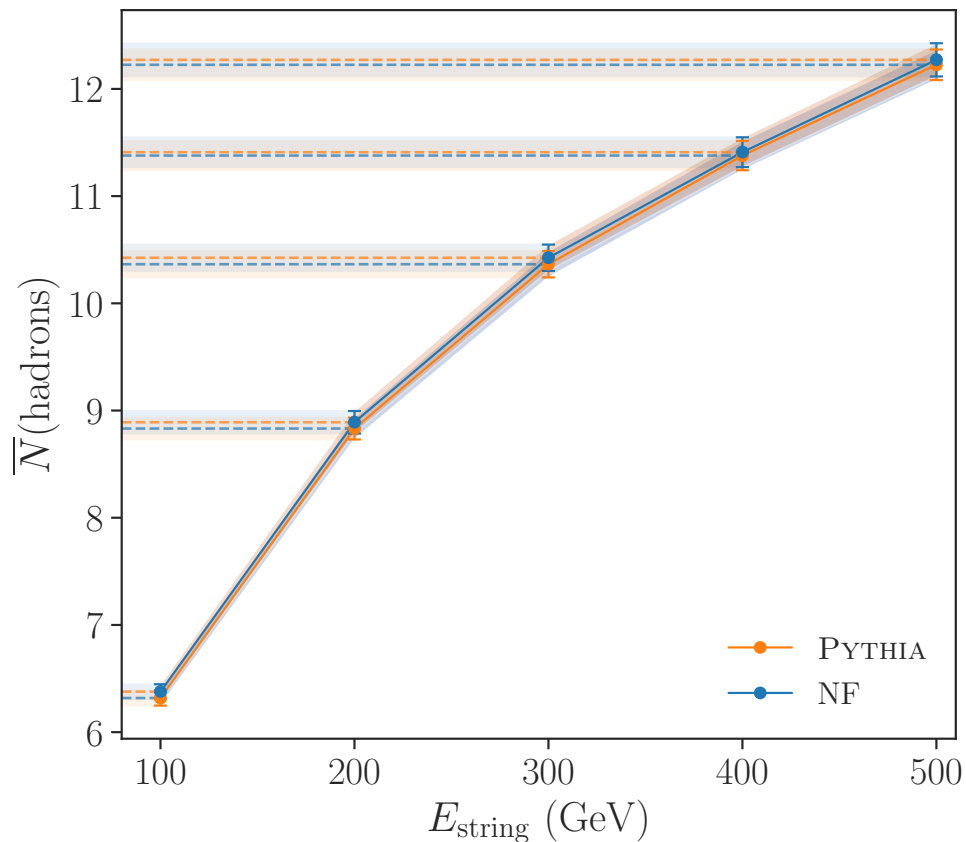
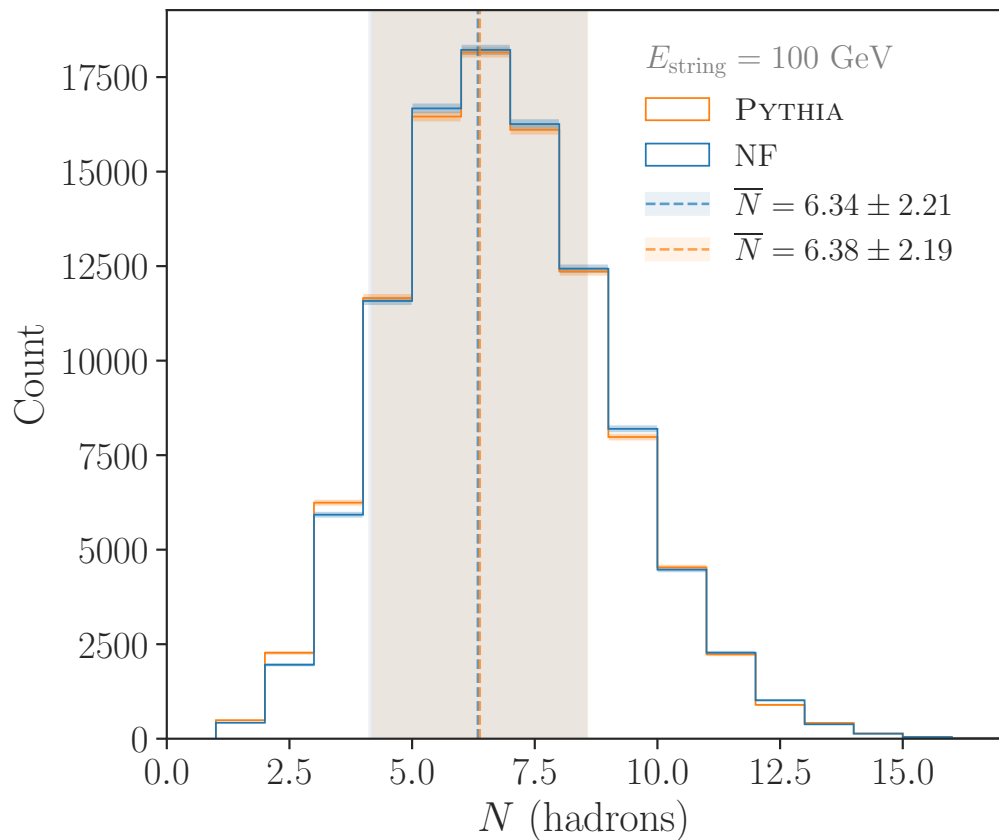
INN learned mapping



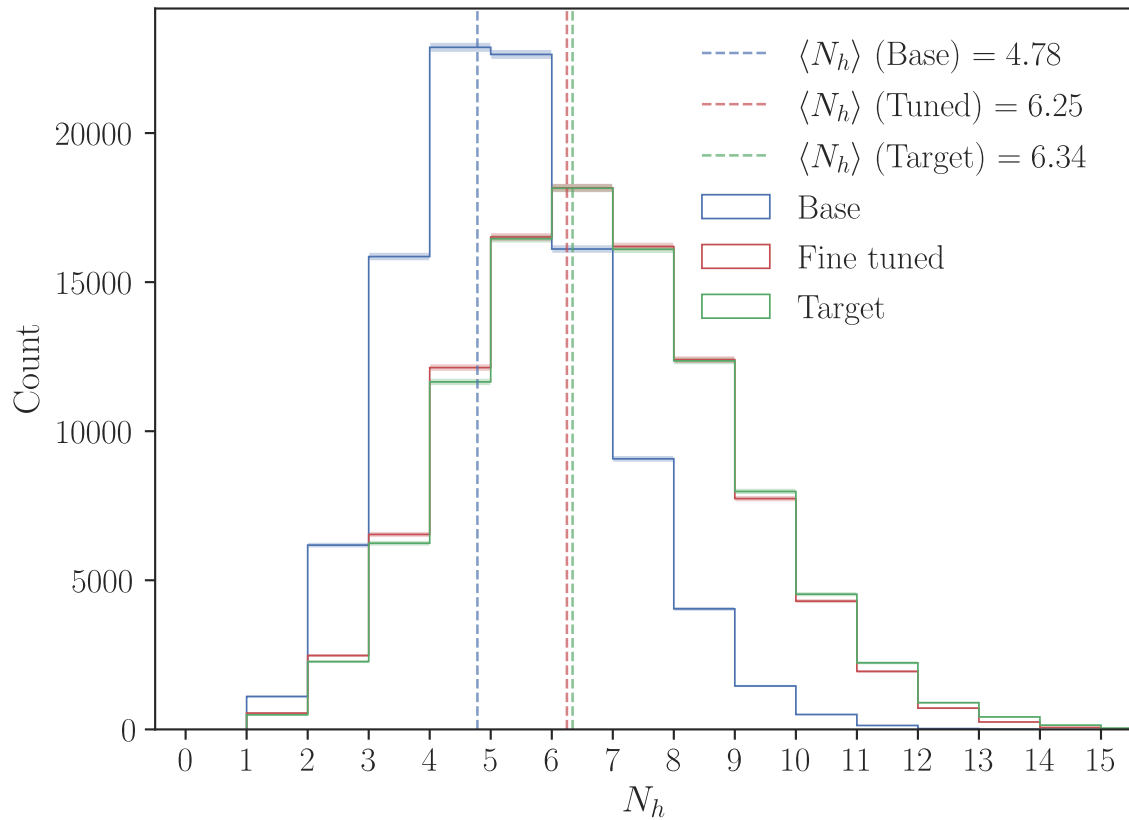
Validation: single emission kinematics



Validation: global observable (hadron multiplicity N)



Toy example



Toy example

